Encoding Compositionality in Classical Planning Solutions

MOTIVATION When trying to understand whether a skill can be transfer, a user may inquire about the purpose each action has in achieving the goal in. To address this, we propose using a structure called string diagrams from category theory to trace literals and predicates and validate compositionality between plans. CATEGORY THEORY & STRING DIAGRAMS A category (C) is: A set of **objects** {*A*, *B*, *C*, ... } A set of **morphisms** $\{f, g, h, ...\}$ Where every object has an identity morphism, id_A **Composition operator**, •, that is *associative* with identity morphisms as *unitors* A symmetric monoidal category (M), adds: + **Tensor product**, \otimes , which is the product of M with itself that is *associative* and has *unitor isomorphisms* + Braiding isomorphism where $B_{\{X,Y\}}: X \otimes Y \to Y \otimes X$ A string diagram is the graphical syntax for symmetric monoidal categories, where **boxes are morphisms** and **strings are objects**. STRING DIAGRAMS FOR PDDL Domain File Problem File (Pre-condition) Predicate (Pre-condition) Literal) handempty clear ?x ontable ?x clear b ontable b pick-up pick-up holding b holding ?x ¬ ontable ?x ¬ clear ?x ◀ \neg ontable b ¬ handempty ¬ clear b 🔰 handempty (Effect) Predicate (Effect) Literal Action Action

Use compositionality to validate transferability of skills

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BENEFITS

- Transferability of skills is a proof-by-construction
 - A corresponding graphical syntax for mathematical
 - expressions whose layout is determined by \circ and \otimes Additional context for how parameters populate the predicates
 - Deformation invariance property that allows you to slide boxes to find alternate plans

LIMITATIONS

- PDDL extensions supported are restricted. We have not defined string diagram encodings for quantifiers, equalities, and other extensions.
- We are unable to encode relationships between positive and negated version of a literal. They are currently treated as independent information under the closed world assumption. The visualization does not scale effectively to long plans with many actions.

FUTURE WORK

Functors (maps between categories)

- Relate composition of actions in domain specific language (e.g. PDDL) to conceptual models of plans to add semantics
- Relate symbolic plans to geometric plans
- Visualization
- Sliding boxes along strings to view alternative plans.
- Scale the length of the strings or the height of the boxes according to some solver metadata, such as cost, or a realworld parameter, such as time to execute.
- Interactions such as highlighting the strings of a particular literal in order to witness its path through the plan